Exploring Energy-Latency Tradeoffs for Sensor Network Broadcasts

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Question???



Sensor Application #1

- Code Update Application
 - E.g., Trickle [Levis et al., NDSI 2004]
- Updates Generated
 Once Every Few Weeks
 - Reducing energy consumption is important
 - Latency is not a major concern



Sensor Application #2

- Short-Term Event Detection
 - E.g., Directed Diffusion [Intanagonwiwat et al., MobiCom 2000]
- Intruder Alert for Temporary, Overnight Camp
 - □ Latency is critical
 - With adequate power supplies, energy usage is not a concern



Energy-Latency Options



Sleep Scheduling Protocols

- Nodes have two states: active and sleep
- At any given time, some nodes are active to communicate data while others sleep to conserve energy
- Examples
 - □ IEEE 802.11 Power Save Mode (PSM)
 - Most complete and supports broadcast
 - Not necessarily directly applicable to sensors
 - □ S-MAC/T-MAC



IEEE 802.11 PSM

- Nodes are assumed to be synchronized
- Every beacon interval (BI), all nodes wake up for an ATIM window (AW)
- During the AW, nodes advertise any traffic that they have queued
- After the AW, nodes remain active if they expect to send or receive data based on advertisements; otherwise nodes return to sleep until the next BI

Protocol Extreme #1









Protocol Extreme #2











Probability-Based Broadcast Forwarding (PBBF)

- Introduce two parameters to sleep scheduling protocols: p and q
- When a node is scheduled to sleep, it will remain active with probability q
- When a node receives a broadcast, it sends it immediately with probability p
 - □ With probability (1-*p*), the node will wait and advertise the packet during the next AW before rebroadcasting the packet

PBBF Comments

- p=0, q=0 equivalent to the original sleep scheduling protocol
- *p*=1, *q*=1 approximates the "always on" protocol
 Still have the ATIM window overhead
- Effects of *p* and *q* on metrics:

	Energy	Latency	Reliability
p↑		\downarrow	\downarrow
		if <i>q</i> > 0	if <i>q</i> < 1
$q\uparrow$	↑	\downarrow	\uparrow
		if <i>p</i> > 0	if <i>p</i> > 0

Analysis: Reliability

- Bond (edge) percolation theory
 - Determines the connectivity of a random graph
 - Different from Haas' Gossip-Based Routing which used site (vertex) percolation theory
- A phase transition occurs when the probability of an edge between two vertices is greater than the critical value

In this phase, the probability that an infinitely large cluster exists in a graph is close to one

 A phase transition occurs when the probability of an edge is less than the critical value
 In this phase, the probability that an infinitely large cluster exists in the graph is close to zero

Analysis: Reliability

In PBBF, the probability that a broadcast is received on a link is:

pq + (1-p)

- Thus, if pq + (1-p) is greater than a critical value, then every broadcast reaches most of the nodes in the network
- Tested PBBF on grid topology with ideal MAC and physical layers

Answer = 0.5



Analysis: Reliability

Phase transition when:

pq + (1-p) ≈ 0.8-0.85

- Larger than bond percolation threshold
 - Boundary effects
 Different metric
- Still shows phase transition





Analysis: Latency Shortest Paths and Reliability







Analysis: Energy-Latency Tradeoff



Application Results

- Simulated code distribution application in *ns-2*, where a base station periodically sends patches for sensors to apply
 - □ 50 nodes
 - □ Average One-Hop Neighborhood Size = 10
 - □ Uniformly random node placement in square area
 - Topology connected
 - □ Full MAC layer

Application: Energy and Latency



Application: Reliability

- Different reliability metric
- Average fraction of broadcasts received per node
- Better fit for application



Work In Progress

- Dynamically adjusting *p* and *q* to converge to userspecified QoS metrics
- E.g., Energy and latency are specified
- Subject to those constraints, p and q are adjusted to achieve the highest reliability possible



Conclusion



Latency

Questions???

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